



Yannick Burkhardt

- 📍 Munich, Germany
- 🎂 August 25, 1997
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Interests

- ⚡ Robot control, trajectory planning, manipulation
- 🤖 Machine learning & vision
- เทร Hiking, football, water polo

Skills

- 💻 C++, Python, Java
- 💻 ROS, DDS, Conan, Git
- 💻 Matlab/ Simulink, Maple, CAD, LaTeX, MS Office

Languages

- 🌐 German: native
- 🌐 English: TOEFL iBT 92%
- 🌐 Spanish

Education

Apr. 2024 – Present	Technical University of Munich PhD candidate in Smart Robotics Lab Event-based visual perception for robot control
Oct. 2020 – Jul. 2023	Technical University of Munich M.Sc. Robotics, Cognition, Intelligence (Grade: 1.1) Technológico de Costa Rica (Exchange)
Oct. 2016 – Feb. 2020	Karlsruhe Institute of Technology B.Sc. Mechatronics and Information Technology (Grade: 1.6)
Aug. 2008 – Jun. 2016	Alexander-von-Humboldt-Gymnasium Allgemeine Hochschulreife (Grade: 1.0)

Work Experience

Aug. 2023 – Feb. 2024	Agile Robots AG Robot Software Engineer Robot control framework implementation
Oct. 2020 – Jan. 2023	Agile Robots AG Working Student & Master Thesis Visual servo control for deep-learning based robot grasping, kinematic calibration
Oct. 2019 – May 2020	LEONI Elocab Ltd. Internship in Kitchener, Canada Cable construction and testing
Oct. 2018 – Aug. 2019	Research Center for Information Tech. Research Assistant & Bachelor Thesis Shared Control for commercial vehicle

Publications

- Yannick Burkhardt et al. *Multi-fingered Dynamic Grasping for Unknown Objects*. 2024 IEEE-RAS International Conference on Humanoid Robots.
- Balint Varga, Arash Shahirpour, Yannick Burkhardt et al. *Validation of Cooperative Shared-Control Concepts for Large Vehicle-Manipulators*. 2020 IEEE Conference on Control Technology and Applications (CCTA).
- Balint Varga, Yannick Burkhardt et al. *Shared-Control Concepts for Large Vehicle-Manipulators*. 2020 IEEE 29th International Symposium on Industrial Electronics (ISIE).

Awards

PhD scholarship from the Munich Center for Machine Learning (2024)
M.Sc. passed with high distinction (2023): top 1.5% graduate
5×Deutschlandstipendium (2017 – 2023)